

	δ势	线性	谐振子	库仑κ = Ze <sup>2</sup>
	$\mu = \hbar = \gamma = 1$	$\mu = \hbar = F = 1$	$\mu = \hbar = \omega = 1$	$\mu = \hbar = \kappa = 1$
能量[E]	$\mu\gamma^2/\hbar^2$	$(\hbar^2 F^2/\mu)^{1/3}$	$\hbar\omega$	$\mu\kappa^2/\hbar^2$
长度[L]	$\hbar^2/\mu\gamma$	$(\hbar^2/\mu F)^{1/3}$	$\sqrt{\hbar/\mu\omega}$	$\hbar^2/\mu\kappa$
时间[T]	$\hbar^3/\mu\gamma^2$	$(\hbar\mu/F^2)^{1/3}$	$1/\omega$	$\hbar^3/\mu\kappa^2$
速度[v]	$\gamma/\hbar$	$(\hbar F/\mu^2)^{1/3}$	$\sqrt{\hbar\omega/\mu}$	$\kappa/\hbar$
动量[p]	$\mu\gamma/\hbar$	$(\hbar\mu F)^{1/3}$	$\sqrt{\hbar\mu\omega}$	$\mu\kappa/\hbar$

### 1. 数学速查

$$\varepsilon_{ijk}\varepsilon_{lmn} = \begin{vmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{vmatrix}$$

$$\sum_{i=1}^3 \varepsilon_{ijk}\varepsilon_{imn} = \delta_{jm}\delta_{kn} - \delta_{jn}\delta_{km}$$

$$(\vec{A} \times \vec{B})_k = \sum_{ij} \varepsilon_{kij} A_i B_j$$

$$\nabla = \hat{r} \frac{\partial}{\partial r} + \frac{1}{r} \hat{\theta} \frac{\partial}{\partial \theta} + \frac{1}{r \sin \theta} \hat{\phi} \frac{\partial}{\partial \phi}$$

$$\nabla \cdot \vec{u} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta u_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} u_\phi$$

$$[A, BC] = B[A, C] + [A, B]C$$

$$[AB, C] = A[B, C] + [A, C]B$$

定义 1.1 (连带 Legendre 多项式):

$$(1 - \xi^2) \frac{d^2 P}{d\xi^2} - 2\xi \frac{dP}{d\xi} + \left( l(l+1) - \frac{m^2}{1 - \xi^2} \right) P = 0$$

$$P_l^m(x) = \frac{1}{2^l l!} (1 - x^2)^{\frac{m}{2}} \frac{d^{l+m}}{dx^{l+m}} (x^2 - 1)^l$$

定理 1.2 (连带 Legendre 多项式的正交性):

$$\int_{-1}^1 P_k^m(\xi) P_l^m(\xi) d\xi = \frac{2}{2l+1} \frac{(l+m)!}{(l-m)!} \delta_{kl}$$

定义 1.3 (Legendre 多项式):

$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l$$

定理 1.4 (Legendre 多项式的正交性):

$$\int_{-1}^1 P_k(x) P_l(x) dx = \frac{2}{2l+1} \delta_{kl}$$

定理 1.5 (厄米多项式的正交性):

$$\int_{-\infty}^{+\infty} H_m(\xi) H_n(\xi) e^{-\xi^2} d\xi = \sqrt{\pi} 2^n n! \delta_{mn}$$

定理 1.6 (厄米多项式的递推关系):

$$H_{n+1}(\xi) - 2\xi H_n(\xi) + 2n H_{n-1}(\xi) = 0$$

定义 1.7 (合流超几何微分方程):

$$z \frac{d^2 y}{dz^2} + (\gamma - z) \frac{dy}{dz} - \alpha y = 0$$

定义 1.8 (合流超几何函数):

$$F(\alpha, \gamma, z) = \sum_{k=0}^{\infty} \frac{\alpha_k z^k}{\gamma_k k!}$$

$$\text{where } \alpha_k = \alpha(\alpha+1)\dots(\alpha+k-1) + iy$$

$$\gamma_k = \gamma(\gamma+1)\dots(\gamma+k-1) - iy$$

定理 1.9 (δ函数的性质):

$$\delta(ax) = \frac{1}{|a|} \delta(x)$$

$$\delta(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{ikx} dk$$

$$x\delta(x) = 0$$

$$\delta(f(x)) = \sum_i \frac{\delta(x - x_i)}{|f'(x_i)|}$$

定义 1.10 (三维δ函数): 假设已定义一维 Dirac 函数δ(x), 那么

$$\delta(\vec{r}) = \delta(x)\delta(y)\delta(z)$$

$$= \frac{1}{r^2 \sin \theta} \delta(r)\delta(\theta)\delta(\phi)$$

$$= \frac{1}{\rho} \delta(\rho)\delta(\phi)\delta(z)$$

定义 1.11 (球谐函数):

$$Y_{lm}(\theta, \phi)$$

$$= (-1)^m \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos \theta) e^{im\phi}$$

$$Y_{00} = \frac{1}{\sqrt{4\pi}}, Y_{10} = \sqrt{\frac{3}{4\pi}} \cos \theta$$

$$Y_{1\pm 1} = \mp \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\phi}$$

$$Y_{20} = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$$

$$Y_{2\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \cos \theta \sin \theta e^{\pm i\phi}$$

$$Y_{2\pm 2} = \frac{1}{2} \sqrt{\frac{15}{8\pi}} \sin^2 \theta e^{\pm 2i\phi}$$

定理 1.12 (球谐函数的完备性): 平方可积的球谐函数形成了一个希尔伯特空间

$$\iint Y_{l'm'} Y_{lm} \sin \theta d\theta d\phi = \delta_{ll'} \delta_{mm'}$$

$$\sum_{l=0}^{+\infty} \sum_{m=-l}^{+l} Y_{lm}(\theta, \phi) Y_{l'm'}^*(\theta', \phi')$$

$$= \frac{1}{\sin \theta} \delta(\theta - \theta') \delta(\phi - \phi')$$

定理 1.13 (球谐函数的递推性质):

$$\frac{z}{r} Y_{lm} = \cos \theta Y_{lm}$$

$$= a_{lm} Y_{l+1,m} + a_{l-1,m} Y_{l-1,m}$$

$$= b_{l-1, -(m+1)} Y_{l-1, m+1} - b_{lm} Y_{l+1, m+1}$$

$$\frac{x - iy}{r} Y_{lm} = e^{-i\phi} \sin \theta Y_{lm}$$

$$= -b_{l-1, m-1} Y_{l-1, m-1} + b_{l, -m} Y_{l+1, m-1}$$

$$a_{lm} = \sqrt{\frac{(l+1)^2 - m^2}{(2l+1)(2l+3)}}$$

$$b_{lm} = \frac{\sqrt{(l+m+1)(l+m+2)}}{(2l+1)(2l+3)}$$

定理 1.14 (傅里叶变换):

$$f(x) = \frac{1}{\sqrt{2\pi}} \int e^{ikx} g(k) dk$$

$$g(k) = \frac{1}{\sqrt{2\pi}} \int e^{-ikx} f(x) dx$$

定理 1.15 (正交对角化):

$$A = PDP^{-1}$$

$$D = \begin{pmatrix} \lambda_1 & & \\ & \dots & \\ & & \lambda_n \end{pmatrix}, P = (v_1 \dots v_n)$$

$$\int_{-\infty}^{+\infty} e^{-a^2 x^2} dx = \frac{\sqrt{\pi}}{|a|}$$

$$\int_0^{+\infty} r^n e^{-r/a} dr = n! a^{n+1}$$

### 2. 算符

$$\vec{p} = -i\hbar \nabla$$

$$\vec{p}^2 = -\hbar^2 \nabla \cdot \nabla$$

$$\vec{p}_r = \frac{1}{2} (\hat{r} \cdot \vec{p} + \vec{p} \cdot \hat{r})$$

$$= -i\hbar \left( \frac{\partial}{\partial r} + \frac{1}{r} \right)$$

$$= -\hbar^2 \frac{1}{r^2} \frac{\partial^2}{\partial r^2} r^2 \frac{\partial}{\partial r}$$

$$\vec{p}^2 = \frac{1}{r^2} \vec{l}^2 + \vec{p}_r^2$$

$$[x_\alpha, p_\beta] = i\hbar \delta_{\alpha\beta}$$

$$[l_\alpha, x_\beta] = \varepsilon_{\alpha\beta\gamma} i\hbar x_\gamma$$

$$[l_\alpha, p_\beta] = \varepsilon_{\alpha\beta\gamma} i\hbar p_\gamma$$

$$[l_\alpha, l_\beta] = \varepsilon_{\alpha\beta\gamma} i\hbar l_\gamma$$

$$[\vec{r}, H] = \frac{i\hbar}{m} \vec{p}$$

公设 2.1 (Schödinger Equation):

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle = H |\psi\rangle$$

### 3. 中心力场

定理 3.1 (中心力场中运动粒子的哈密顿量):

$$H = \frac{p^2}{2\mu} + V(r)$$

$$= \frac{p_r^2}{2\mu} + \frac{\vec{l}^2}{2\mu r^2} + V(r)$$

$$= -\frac{\hbar^2}{2\mu} \left( \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) + \frac{\vec{l}^2}{2\mu r^2} + V(r)$$

定理 3.2 (中心力场中能量本征方程): 一般将势函数分离变量为

$$\Psi(r, \theta, \phi) = R(r) Y_{lm}(\theta, \phi)$$

$$R_{20} = \frac{1}{\sqrt{2} a^{3/2}} \left( 1 - \frac{r}{2a} \right) e^{-r/2a}$$

令χ(r) = rR(r), 有

$$\chi_l'' + \left( \frac{2\mu}{\hbar^2} (E - V) - \frac{l(l+1)}{r^2} \right) \chi_l = 0$$

3.1. 三维各向同性谐振子

$$V(r) = \frac{1}{2} \mu \omega^2 r^2$$

能量本征值为

$$E_N = \left( N + \frac{3}{2} \right) \hbar \omega$$

$$N = 2n_r + l$$

$$n_r, l = 0, 1, 2, \dots$$

简并度为

$$f_N = \frac{1}{2} (N+1)(N+2)$$

径向本征函数为

$$R_{n_r, l}(r) = a^{l+3/2} \sqrt{\frac{2^{l+2-n_r} (2l+2n_r+1)!}{\sqrt{\pi} n_r! ((2l+1)!!)^2}}$$

$$r^l e^{-a^2 r^2/2} F\left(-n_r, l + \frac{3}{2}, a^2 r^2\right)$$

如果在直角坐标系中求解, 这两套本征态通过么正变换联系起来

$$\varphi_{01m} = \sum_{n_x n_y n_z} \psi_{n_x n_y n_z}^* \varphi_{01m} d\tau$$

$$\begin{pmatrix} \varphi_{011} \\ \varphi_{01-1} \\ \varphi_{010} \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_{100} \\ \psi_{101} \\ \psi_{101} \end{pmatrix}$$

### 3.2. 氢原子

化为单体问题后有

$$V(r) = -\frac{e^2}{r}$$

定义 3.2.1 (Bohr 半径):  $a = \frac{\hbar^2}{\mu e^2}$

能量本征值为

$$E_n = -\frac{\mu e^4}{2\hbar^2 n^2} = -\frac{e^2}{2a n^2}$$

$$n = n_r + l + 1$$

$$n_r = 0, 1, 2, \dots$$

径向本征函数为

$$R_{nl}(r) = \frac{2}{a^{3/2} n^2 (2l+1)!} \sqrt{\frac{(n+l)!}{(n-l-1)!}} l_z = -i\hbar \frac{\partial}{\partial \phi}$$

$$e^{-\xi/2} \xi^l F(-n_r, 2l+2, \xi)$$

$$\text{where } \xi = \frac{2r}{na}$$

简并度为

$$f_N = \frac{1}{2} (N+1)(N+2)$$

$$R_{30} = \frac{2}{3\sqrt{3} a^{3/2}} \left( 1 - \frac{2r}{3a} + \frac{2}{27} \frac{r^2}{a^2} \right) e^{-r/3a}$$

本征函数为

$$\psi_{nlm} = R_{nl}(r) Y_{lm}(\theta, \phi)$$

简并度为

$$f_n = \sum_{l=0}^{n-1} (2l+1) = n^2$$

统计意义上, 电子的电流密度(绕 z 轴的环电流密度)为

$$\vec{j} = \frac{ie\hbar}{2\mu} (\psi^* \nabla \psi - \psi \nabla \psi^*)$$

$$= -\frac{e\hbar m}{\mu} \frac{1}{r \sin \theta} |\psi_{nlm}|^2 \hat{e}_\phi$$

$$\vec{M} = -\frac{e\hbar m}{2\mu c} \hat{z} \int |\psi_{nlm}|^2 d\tau$$

$$= -\frac{e\hbar m}{2\mu c} \hat{z}$$

定义 3.2.2 (Bohr 磁子):

$$\mu_B = \frac{e\hbar}{2\mu c}$$

定义 3.2.3 (Larmor 频率):

$$\omega_L = \frac{eB}{2\mu c}$$

类氢离子(He<sup>+</sup>, Li<sup>++</sup>, ...)需将核电荷数+e换成+Ze, 约化质量换成相应的μ

$$E_n = -\frac{\mu e^4 Z^2}{2\hbar^2 n^2} = -\frac{e^2 Z^2}{2a n^2}$$

### 4. 角动量和自旋

#### 4.1. 角动量

定义 4.1.1 (角动量):  $\vec{l} = \vec{r} \times \vec{p}$

$$l_x = i\hbar \left( \sin \phi \frac{\partial}{\partial \theta} + \cot \theta \cos \phi \frac{\partial}{\partial \phi} \right)$$

$$l_y = i\hbar \left( -\cos \phi \frac{\partial}{\partial \theta} + \cot \theta \sin \phi \frac{\partial}{\partial \phi} \right)$$

$$l_z = -i\hbar \frac{\partial}{\partial \phi}$$

$$\vec{l} \times \vec{l} = i\hbar \vec{l}$$

$$\vec{l}^2 = l_z^2 + l_y^2 + l_x^2$$

$$= -\frac{\hbar^2}{\sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} l_z^2$$

定义 4.1.2 (角动量升降算符):

$$J_{\pm} = J_x \pm iJ_y$$

$$J_{\pm} J_{\mp} = \vec{J}^2 - J_z^2 \pm \hbar J_z$$

$$\vec{J}^2 = \frac{1}{2}(J_+ J_- + J_- J_+) + J_z^2$$

$$[J_+, J_-] = 2\hbar J_z, [J_z, J_{\pm}] = \pm \hbar J_{\pm}$$

$$[J_x, J_{\pm}] = \mp \hbar J_z, [J_y, J_{\pm}] = \mp \hbar J_z$$

$$[J^2, J_{\pm}] = 0$$

$$Y_{lm_l \chi_{\frac{1}{2}}} = \sqrt{\frac{l+m_l+1}{2l+1}} \Psi_{l, j=l+\frac{1}{2}, m_l+\frac{1}{2}}$$

$$-\sqrt{\frac{l-m_l}{2l+1}} \Psi_{l, j=l-\frac{1}{2}, m_l+\frac{1}{2}}$$

$$Y_{lm_l \chi_{-\frac{1}{2}}} = \sqrt{\frac{l-m_l+1}{2l+1}} \Psi_{l, j=l+\frac{1}{2}, m_l-\frac{1}{2}}$$

$$+\sqrt{\frac{l+m_l}{2l+1}} \Psi_{l, j=l-\frac{1}{2}, m_l-\frac{1}{2}}$$

定义 4.4.1 (自旋三重态与单态): 选择  $\{S^2, S_z\}$  作为对易自旋力学量完全集

$$\begin{array}{ccc} S^2 \chi_{SM_S} & = & S(S+1)\hbar^2 \chi_{SM_S} \\ S_z \chi_{SM_S} & = & M_S \hbar \chi_{SM_S} \\ \chi_{SM_S} & & S \quad M_S \\ \alpha_1 \alpha_2 & & 1 \quad 1 \\ \frac{1}{\sqrt{2}}(\alpha_1 \beta_2 + \beta_1 \alpha_2) & & 1 \quad 0 \\ \beta_1 \beta_2 & & 1 \quad -1 \\ \frac{1}{\sqrt{2}}(\alpha_1 \beta_2 - \beta_1 \alpha_2) & & 0 \quad 0 \\ (\vec{\sigma}_1 \cdot \vec{\sigma}_2)^2 & = & 3 - 2\vec{\sigma}_1 \cdot \vec{\sigma}_2 \end{array}$$

## 4.2. 自旋

定义 4.2.1 (Pauli 矩阵):

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\sigma_{\alpha} \sigma_{\beta} = \delta_{\alpha\beta} + i \sum_{\gamma} \epsilon_{\alpha\beta\gamma} \sigma_{\gamma}$$

$$\sigma_{\alpha} = \sigma_{\alpha}^{\dagger}$$

定义 4.2.2 (磁矩算符):

$$\vec{\mu} = g \frac{\mu_B}{\hbar} \vec{j}$$

$$\vec{j} = \vec{s} + \vec{l}, g_l = -1, g_s = -2$$

定义 4.2.3 (磁矩磁场相互作用能):

$$W = -(\vec{\mu}_l + \vec{\mu}_s) \cdot \vec{B}$$

定义 4.2.4 (旋量波函数):

$$\psi(\vec{r}, s_z) = \begin{pmatrix} \psi_1(\vec{r}, +\frac{\hbar}{2}) \\ \psi_2(\vec{r}, -\frac{\hbar}{2}) \end{pmatrix}$$

在哈密顿量不含自旋或可以表示成与自旋部分之和的时候

$$\psi(\vec{r}, s_z) = \psi(\vec{r}) \chi(s_z)$$

$$\alpha = \chi_{+1/2}(s_z) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\beta = \chi_{-1/2}(s_z) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

## 4.3. 耦合与非耦合表象的基底变换

$$|j_1 j_2 j m\rangle = \sum_{m_1=-j_1}^{j_1} \sum_{m_2=-j_2}^{j_2} C_{j_1 m_1 j_2 m_2}^{j_1 j_2 j m} |j_1 m_1 j_2 m_2\rangle$$

$$C_{j_1 m_1 j_2 m_2}^{j_1 j_2 j m} = \langle j_1 m_1 j_2 m_2 | j_1 j_2 j m \rangle$$

## 4.4. 电子耦合与非耦合表象变换

$$\Psi_{l, j=l+\frac{1}{2}, m_j} = \frac{1}{\sqrt{2j}} \begin{pmatrix} \sqrt{j+m_j} Y_{l, m_j-\frac{1}{2}} \\ \sqrt{j-m_j} Y_{l, m_j+\frac{1}{2}} \end{pmatrix}$$

$$\Psi_{l, j=l-\frac{1}{2}, m_j} = \frac{1}{\sqrt{2j+2}} \begin{pmatrix} -\sqrt{j-m_j+1} Y_{l, m_j-\frac{1}{2}} \\ \sqrt{j+m_j+1} Y_{l, m_j+\frac{1}{2}} \end{pmatrix}$$

## 5. 定态微扰

$$H = H_0 + W$$

一些情况下, 基态无简并, 可用非简并微扰论处理基态, 简并微扰论处理激发态.

### 5.1. 非简并微扰论

$$E_n^1 = \langle \psi_n^0 | W | \psi_n^0 \rangle = W_{nn}$$

$$\psi_n^1 = \sum_{m \neq n} \frac{\langle \psi_m^0 | W | \psi_n^0 \rangle}{E_n^0 - E_m^0} |\psi_m^0\rangle$$

$$E_n^2 = \langle \psi_n^0 | W | \psi_n^1 \rangle = \sum_{m \neq n} \frac{|W_{mn}|^2}{E_n^0 - E_m^0}$$

### 5.2. 简并微扰论

对某能级  $n$

$$|\psi^0\rangle = \sum_{\mu=1}^f a_{\mu} |\psi_{n\mu}^0\rangle$$

$$\sum_{\mu} (W_{\mu'\mu} - E_n^1 \delta_{\mu'\mu}) a_{\mu} = 0$$

$$\det(W_{\mu'\mu} - E_n^1 \delta_{\mu'\mu}) = 0$$

$$E_n^1 = E_{n\alpha}^1, \alpha = 1, 2, \dots, f_n$$

## 6. 跃迁

对于哈密顿量不含时的体系, 通过 Schödinger 方程可求解体系随时间的演化, 含时的情况要用含时微扰处理.

### 6.1. 含时微扰

$$H(t) = H_0 + H'(t)$$

$$\Psi(t) = \sum_n C_{nk}(t) e^{-\frac{i}{\hbar} E_n t} |n\rangle, C_{nk}(0) = \delta_{nk} \psi_n(x) = \left(\frac{m\omega}{\pi\hbar}\right)^{\frac{1}{4}} \frac{1}{\sqrt{2^n n!}} H_n(\xi) e^{-\frac{\xi^2}{2}}$$

定理 6.1.1 (一级 Dirac 近似公式): 从  $t=0$  到  $t$  时刻, 体系从  $|k\rangle$  跃迁到  $|k'\rangle$  的概率幅

$$C_{k'k}(t) = \frac{1}{i\hbar} \int_0^t H'_{k'k}(t') e^{i\omega_{k'k} t'} dt$$

$$P_{k'k}(t) = \frac{1}{\hbar^2} \left| \int_0^t H'_{k'k}(t') e^{i\omega_{k'k} t'} dt \right|^2$$

$$H'_{k'k}(t) = \langle k' | H'(t) | k \rangle, \omega_{k'k} = \frac{E_{k'} - E_k}{\hbar}$$

### 6.2. 光的吸收与辐射

$$H = -\vec{D} \cdot \vec{E}$$

## 7. 矩阵形式

定理 7.1 (么正变换): 对 2 套各自正交归一的基矢, 存在么正算符

$$U = \sum_n |b_n\rangle \langle a_n|$$

使得

$$|b_i\rangle = U |a_i\rangle, \dots, |b_n\rangle = U |a_n\rangle$$

$$\langle p|x\rangle = \frac{1}{\sqrt{2\pi\hbar}} e^{-\frac{ipx}{\hbar}}$$

$$\langle x|p\rangle = \frac{1}{\sqrt{2\pi\hbar}} e^{\frac{ipx}{\hbar}}$$

$$\langle p|H|\psi\rangle = \frac{p^2}{2m} \langle p|\psi\rangle + V\left(i\hbar \frac{\partial}{\partial p}\right) \langle p|\psi\rangle$$

## 8. 势阱的解

### 8.1. 一维无限深方势阱

$$E_n = \frac{\pi^2 \hbar^2}{2ma^2} n^2 \text{ where } n = 1, 2, 3, \dots$$

$$\psi_n(x) = \begin{cases} \sqrt{\frac{2}{a}} \sin\left(\frac{n\pi x}{a}\right) & \text{if } 0 < x < a \\ 0 & \text{elsewhere} \end{cases}$$

### 8.2. 一维谐振子

$$V(x) = \frac{1}{2} kx^2$$

$$\frac{d^2\psi}{d\xi^2} + (\lambda - \xi^2)\psi = 0$$

$$\text{where } \omega = \sqrt{\frac{k}{m}}, \lambda = \frac{2E}{\hbar\omega}, \xi = x\sqrt{\frac{m\omega}{\hbar}}$$

$$E_n = \left(n + \frac{1}{2}\right) \hbar\omega$$

$$\text{where } H_n(x) = (-1)^n e^{x^2} \frac{d^n}{dx^n} e^{-x^2}$$

$$a = \sqrt{\frac{m\omega}{2\hbar}} \left(x + \frac{ip}{m\omega}\right)$$

$$a^{\dagger} = \sqrt{\frac{m\omega}{2\hbar}} \left(x - \frac{ip}{m\omega}\right)$$

$$N = a^{\dagger} a$$

$$[a, a^{\dagger}] = 1$$

$$H|n\rangle = \left(n + \frac{1}{2}\right) \hbar\omega |n\rangle$$

$$E_n = \left(n + \frac{1}{2}\right) \hbar\omega$$

$$[N, a] = -a$$

$$[N, a^{\dagger}] = a^{\dagger}$$

$$a|n\rangle = \sqrt{n} |n-1\rangle$$

$$a^{\dagger}|n\rangle = \sqrt{n+1} |n+1\rangle$$

$$|n\rangle = \frac{1}{\sqrt{n!}} (a^{\dagger})^n |0\rangle$$

$$a|0\rangle = 0$$

$$\psi_0(x) = \left(\frac{m\omega}{\pi\hbar}\right)^{\frac{1}{4}} e^{-\frac{m\omega}{2\hbar} x^2}$$

$$\langle x|n\rangle = \frac{1}{\sqrt{n!}} \langle x|(a^{\dagger})^n |0\rangle$$

$$= \frac{1}{\sqrt{2^n n!}} \left(\frac{m\omega}{\pi\hbar}\right)^{\frac{1}{4}}$$

$$\left(\sqrt{\frac{m\omega}{\hbar}} x + \sqrt{\frac{\hbar}{m\omega}} \frac{d}{dx}\right)^n e^{-\frac{m\omega}{2\hbar} x^2} = e^{ik\vec{r}} - \frac{\mu}{2\pi\hbar^2} \int d^3 r' \frac{e^{ik|\vec{r}-\vec{r}'|}}{|\vec{r}-\vec{r}'|} V(\vec{r}') \psi(\vec{r}')$$

## 9. 守恒量

定理 9.1 (Ehrenfest): 若力学量  $A$  不显含时间, 有

$$\frac{d}{dt} \langle A \rangle = \frac{1}{i\hbar} \langle [A, H] \rangle$$

证明: 考虑力学量  $A(t)$  在任意  $|\psi(t)\rangle$  上的演化, 可得

$$\frac{d}{dt} \langle A \rangle = \left\langle \frac{\partial A}{\partial t} \right\rangle + \frac{1}{i\hbar} \langle [A, H] \rangle$$

此外  $A$  不显含时间, 有  $\frac{\partial A}{\partial t} = 0$ .

定理 9.2: 若力学量  $A$  不显含时间, 且  $[A, H] = 0$ , 则  $A$  在任何  $|\psi(t)\rangle$  下的平均值与概率分布均不变.

例 9.1: 中心力场中的守恒量为  $\{H, \vec{l}^2, l_z\}$ .

例 9.2: 自由粒子的态可以用  $\{p_x, p_y, p_z\}$  标记, 对应能量的简并度一般是无穷大.

定理 9.3 (Feynman-Hellmann): 若系统哈密顿量含有某参数  $\lambda$ ,  $E_n$  为哈密顿量的本征值, 相应归一化本征态 (束缚态) 为  $|\psi_n\rangle$ , 有

$$\frac{\partial E_n}{\partial \lambda} = \left\langle \psi_n \left| \frac{\partial H}{\partial \lambda} \right| \psi_n \right\rangle$$

定理 9.4 (位力(virial)): 处于势场  $V(\vec{r})$  中的粒子, 动能算符在定态上的平均值为

$$\langle T \rangle = \frac{1}{2} \langle \vec{r} \cdot \nabla V \rangle$$

推论 9.4.1: 当势能为坐标的  $n$  次齐次函数时, 有

$$\langle T \rangle = \frac{n}{2} \langle V \rangle$$

## 10. Born 近似法

定理 10.1 (Lippman-Schwinger 方程):

$$\psi(\vec{r}) = e^{ik\vec{r}} + \frac{2\mu}{\hbar^2} \int d^3 r' G(\vec{r}, \vec{r}') V(\vec{r}') \psi(\vec{r}')$$

$$= \psi_i(\vec{r}) + \psi_{sc}(\vec{r})$$

$$G(\vec{r}, \vec{r}') = G(\vec{r} - \vec{r}') = -\frac{e^{ik|\vec{r}-\vec{r}'|}}{4\pi|\vec{r}-\vec{r}'|}$$

$$e^{-\frac{i\mu}{\hbar^2} \int d^3 r' \frac{e^{ik|\vec{r}-\vec{r}'|}}{|\vec{r}-\vec{r}'|} V(\vec{r}') \psi(\vec{r}')} = e^{ik\vec{r}} - \frac{\mu}{2\pi\hbar^2} \int d^3 r' \frac{e^{ik|\vec{r}-\vec{r}'|}}{|\vec{r}-\vec{r}'|} V(\vec{r}') \psi(\vec{r}')$$

定义 10.2 (散射边界条件):

$$\psi_{sc}(\vec{r}) \xrightarrow{r \rightarrow \infty} f(\theta, \phi) \frac{e^{ikr}}{r}$$

定理 10.3 (Born 近似方法): 将  $\psi(\vec{r}')$  用零级近似解  $e^{ik\vec{r}'}$  代替

$$\psi(\vec{r}) = e^{ik\vec{r}} - \frac{\mu}{2\pi\hbar^2} \int d^3 r' \frac{e^{ik|\vec{r}-\vec{r}'|}}{|\vec{r}-\vec{r}'|} V(\vec{r}') e^{ik\vec{r}'}$$

$$f(\theta, \phi) = -\frac{\mu}{2\pi\hbar^2} \int d^3 r' e^{-i\vec{q}\vec{r}'} V(\vec{r}')$$

如  $V(\vec{r})$  只与  $r$  有关, 积掉  $\phi$ , 有

$$\blacksquare f(\theta) = -\frac{2\mu}{\hbar^2 q} \int_0^{+\infty} dr' r' \sin(qr') V(r')$$

$$q = 2k \sin(\theta/2)$$

定义 10.4 (散射截面):  $\sigma(\theta, \phi) = \frac{1}{j_1} \frac{d\Omega}{d\Omega}$

$$\sigma(\theta) = |f(\theta)|^2$$